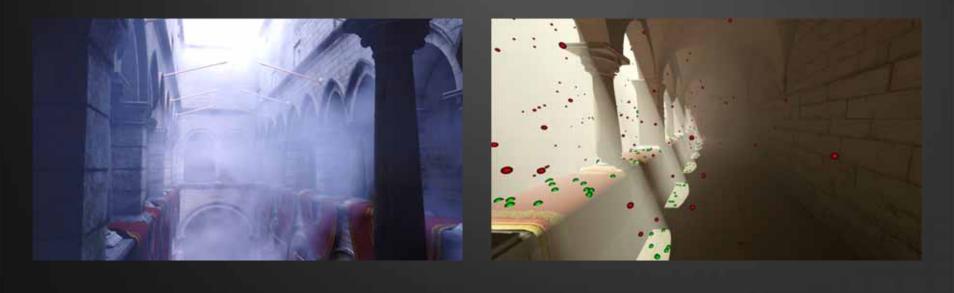
Optimizing Realistic Rendering with Many-Light Methods Real-Time Many-Light Rendering

Carsten Dachsbacher Computer Graphics Group Karlsruhe Institute of Technology



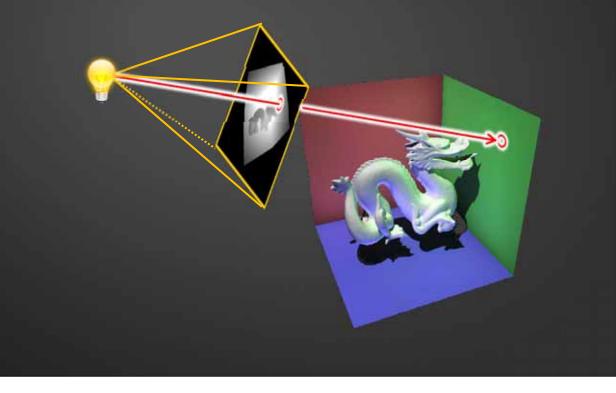
#### Outline

- main difference to offline-methods is visibility computation
  - rasterization instead of raycasting
  - VPL generation
  - lighting and shadowing from VPLs
- high-quality rendering
  - bias compensation in screen-space
  - approximate compensation in participating media rendering



### Visibility Computation for VPL Generation

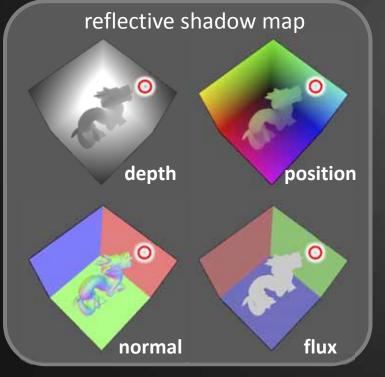
- ▷ real-time rendering  $\leftrightarrow$  mostly diffuse scenes  $\leftrightarrow$  relatively few VPLs (~10<sup>3</sup>)
- if acceleration structure available use ray casting
- VPL generation with rasterization
  - render scene from light
  - observation: visible surfaces = first intersection of light path

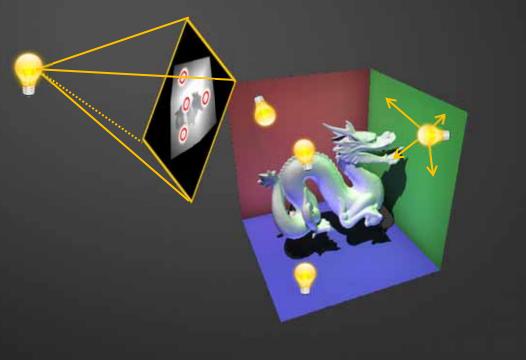




#### **VPL Generation with Rasterization**

- render scene from light into reflective shadow map [DS05]: all information available for creating VPLs and continuing paths
  - single bounce indirect illumination by directly sampling the RSM
  - importance sampling can easily be added [DS06]
- proceed recursively by rendering another RSM





## **Rendering with VPLs**

### Lighting and Shadowing

- many lights can be handled with deferred shading
  - interleaved sampling (problem: detailed normals/geometry) [Seg06]
  - hierarchical shading [NW10]
  - accumulate and filter incident light [SW09]
  - clustered deferred and forward shading [OBA12]



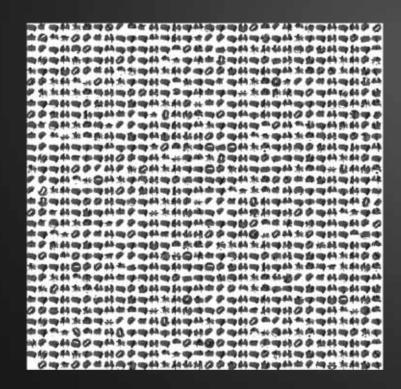
bottleneck: shadow computation

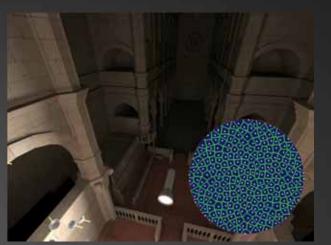


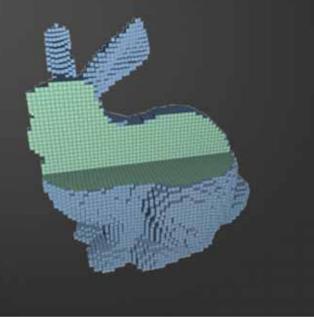
## **Rendering with VPLs**

#### **Shadow Computation**

- …is the real bottleneck with instant radiosity / many lights methods
  - exploit temporal coherency [LSKLA07]
  - sampled visibility
    - voxelization, e.g. [SS10]
    - faster shadow maps





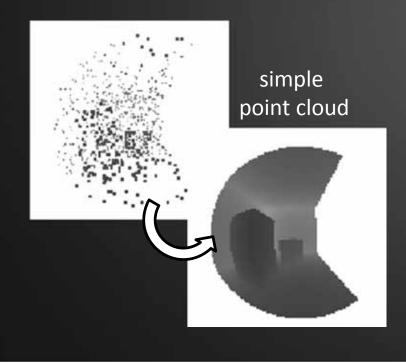


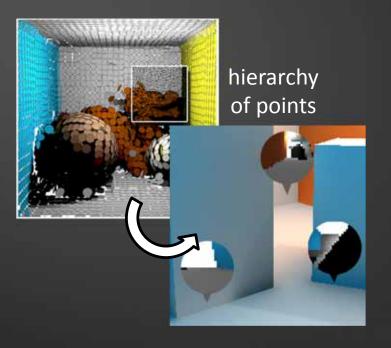




#### **Problem Setting**

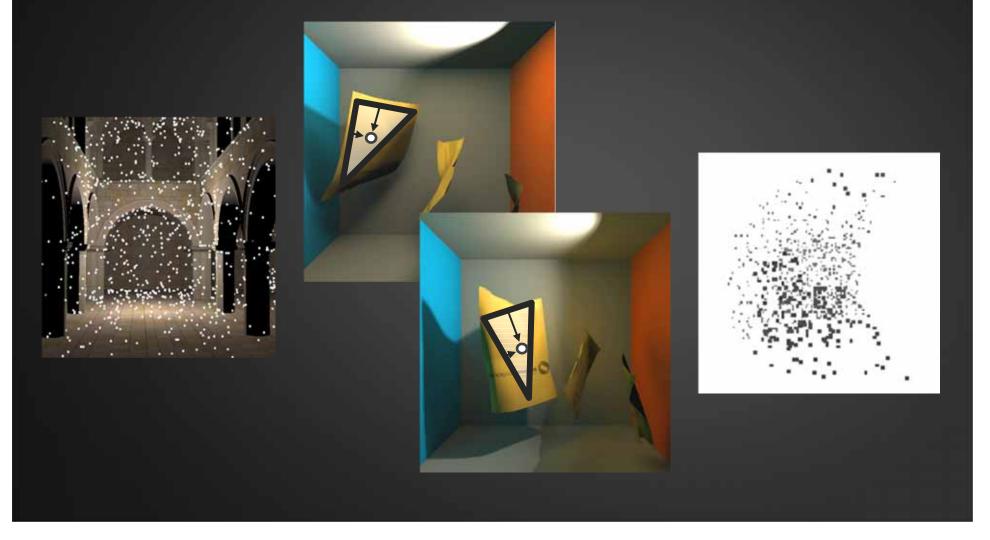
- need many shadow maps of low/moderate resolution
- rendering the scene many times (transformation, ...) is costly
  - what we need is level-of-detail rendering
  - point representations are well-suited for fast, approximate renderings
  - two approaches: simple LOD with no connectivity and water-tight rendering with point hierarchy





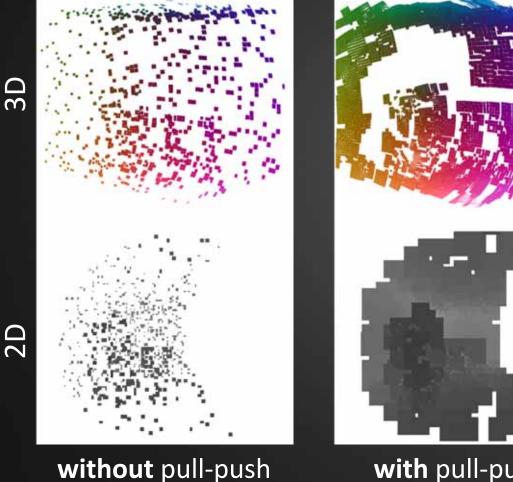
#### **Imperfect Shadow Maps**

- create random sets of point samples (triangle ID + barycentric coords)
- 4k to 16k points per "shadow map" (global parameter)



#### **Imperfect Shadow Maps**

- 4k to 16k points per "shadow map" (global parameter)
- heuristic to reconstruct the surfaces from point samples



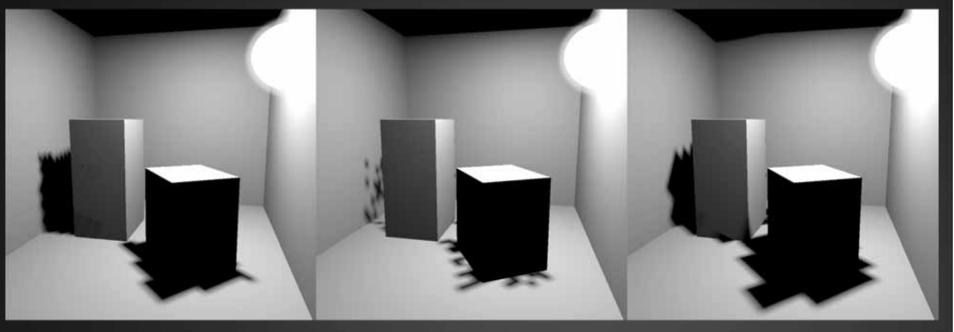
with pull-push

triangle rasterization



#### **Imperfect Shadow Maps**

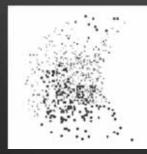




#### triangle rasterization



#### without pull-push



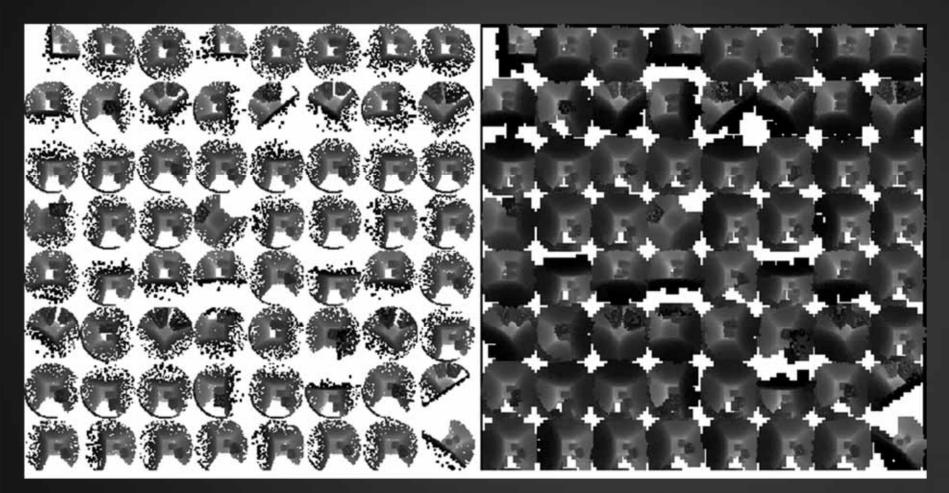
### with pull-push



#### Imperfect Shadow Maps



pull-push in image-space: parallel for thousands of shadow maps

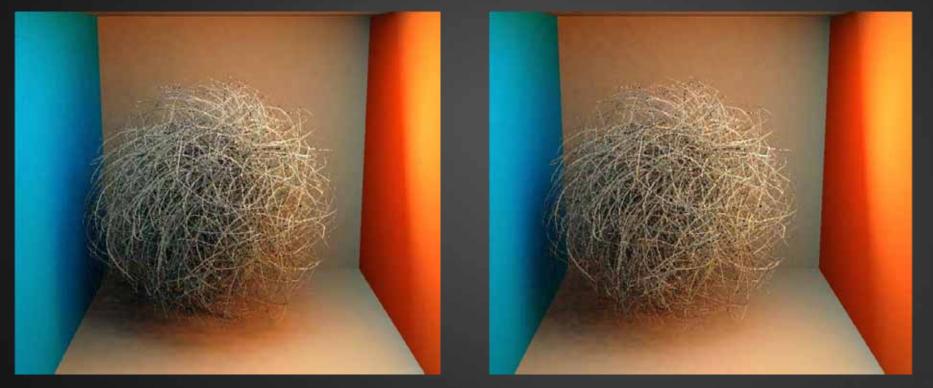


#### without pull-push

with pull-push

#### **Imperfect Shadow Maps**

- ... can render thousands of shadow maps in 100ms
- ... work because errors average out
- ... require playing with parameters



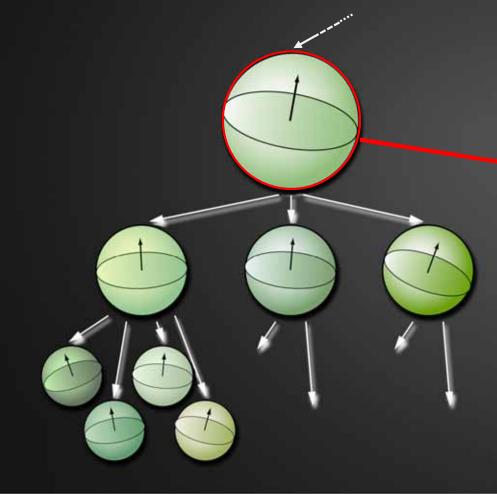
"perfect" shadow maps

imperfect shadow maps



#### **High-Quality Point-based Rendering**

- create random points on surfaces and create hierarchy
- idea of Qsplat: traverse hierarchy until projected size of point primitive is small enough



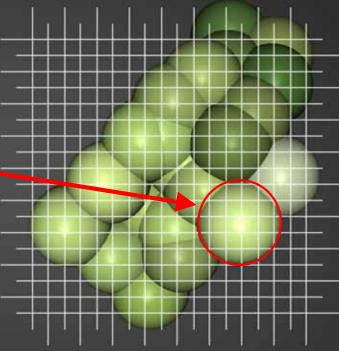
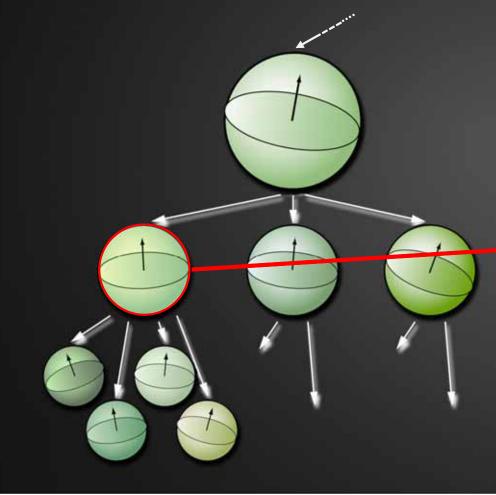


image size >1 pixel traverse <u>children</u>



#### **High-Quality Point-based Rendering**

- create random points on surfaces and create hierarchy
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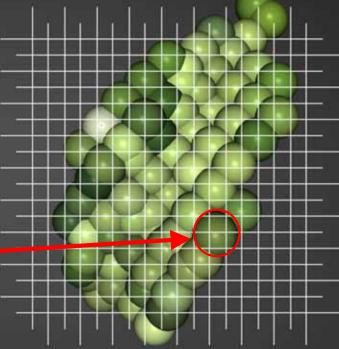
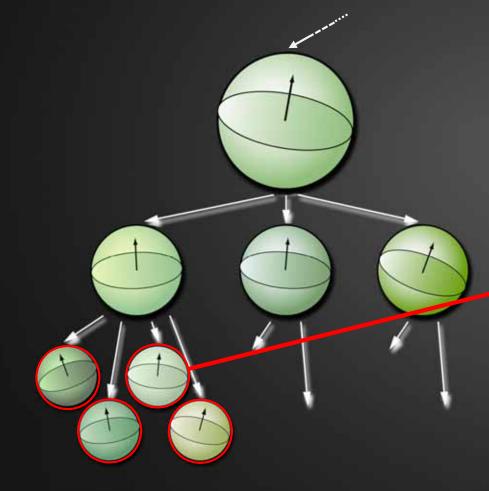


image size >1 pixel traverse <u>children</u>



#### **High-Quality Point-based Rendering**

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- idea of Qsplat: traverse hierarchy until projected size of point primitive is small enough



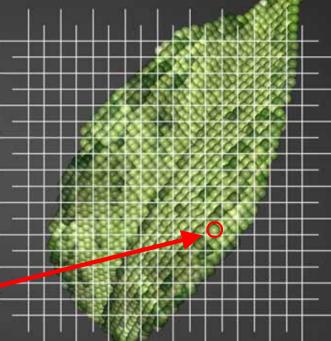
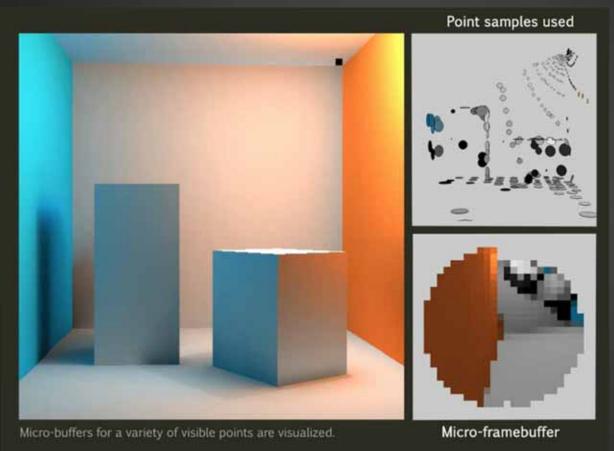


image size <1 pixel render point primitive

#### **Micro-Rendering**

- renders accurate environment maps / depth buffers from point hierarchy
- actually developed for final gathering, using CUDA/OpenCL
- can be used to create (R)SMs (in 2009: ~16k in 100 ms, each 24<sup>2</sup> pixels)



#### Outline

- main difference to offline-methods is visibility computation
  - rasterization instead of raycasting
  - VPL generation
  - lighting and shadowing from VPLs
- high-quality rendering
  - bias compensation in screen-space
  - approximate compensation in participating media rendering



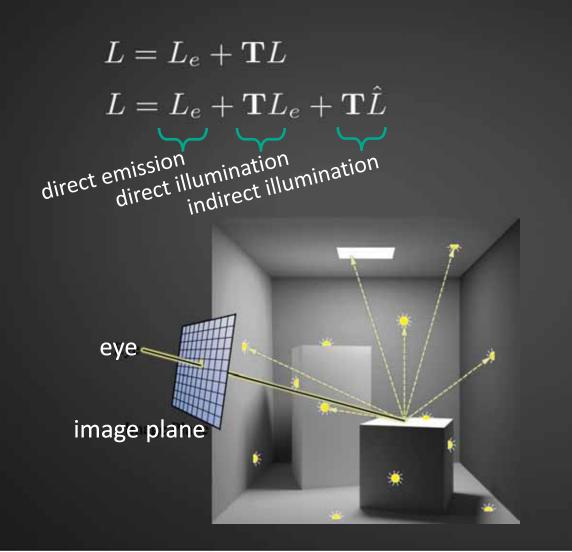


- so far: VPL generation, shading and shadowing
- $\blacktriangleright$  we assume to use VPLs to approximate indirect illumination  $\hat{L}$  only

 $L = L_e + TL$  $L = L_e + TL_e + T\hat{L}$ direct emission direct illumination indirect illumination

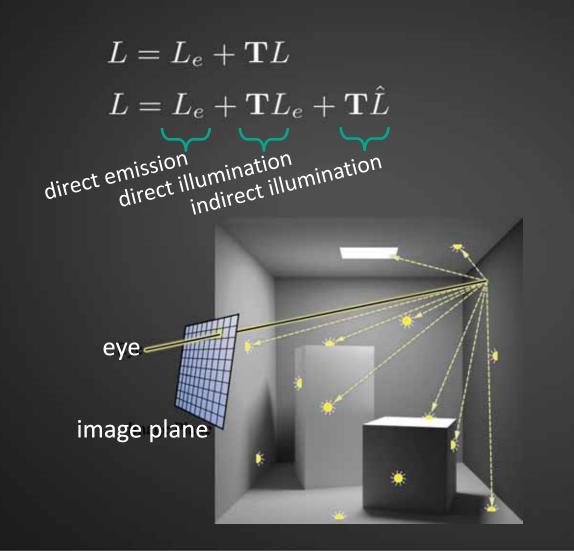


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- $\blacktriangleright$  we assume to use VPLs to approximate indirect illumination  $\hat{L}$  only



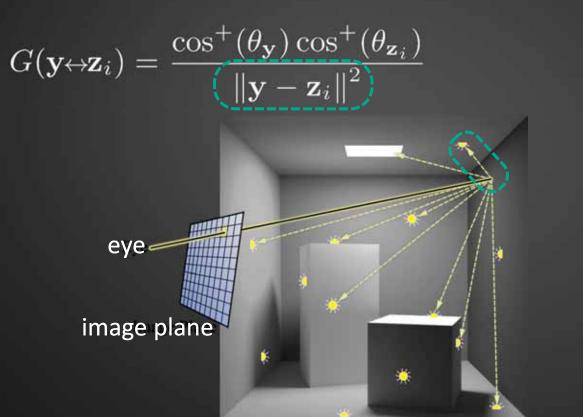


$$L = L_e + \mathbf{T}L_e + \mathbf{T}\hat{L}$$

transport operator:

$$(\mathbf{T}\hat{L})(\mathbf{x} \leftarrow \mathbf{y}) = \sum_{i=1}^{N} f_r(\mathbf{x} \leftarrow \mathbf{y} \leftarrow \mathbf{z}_i) G(\mathbf{y} \leftrightarrow \mathbf{z}_i) V(\mathbf{y} \leftrightarrow \mathbf{z}_i) \hat{L}(\mathbf{y} \leftarrow \mathbf{z}_i)$$

geometry term:





#### reference (slow) rendering



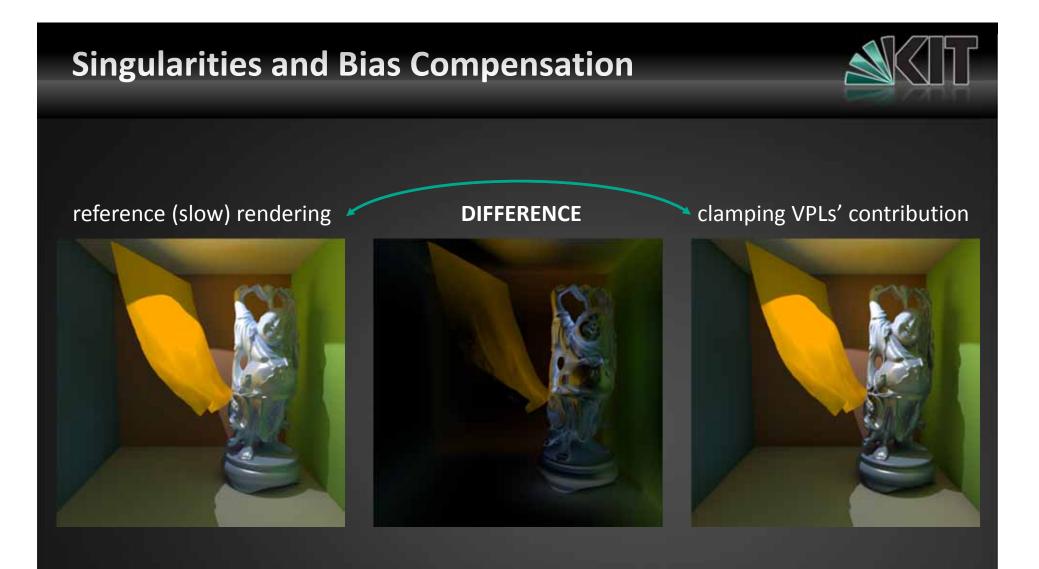
#### fast rendering with few VPLs



#### clamping VPLs' contribution



clamping the contribution of nearby VPLs by bounding the geometry term



clamping removes short distance light transport. How do we restore the missing energy?

## **Bounded and Residual Light Transport**









full LT:  $L_e + \mathbf{T}L_e + \mathbf{T}\hat{L}$ 

bounded indirect LT:  $L_e + \mathbf{T}L_e + \mathbf{T}_b \hat{L}$ 

residual indirect LT:  $\mathbf{T}_r \hat{L}$ 

*b*: user-defined bound

$$\mathbf{T}\hat{L} = \sum_{i=1}^{N} f_r \ G \ V \ \hat{L}$$
$$\mathbf{T}_b \hat{L} = \sum_{i=1}^{N} f_r \ \min(G, b) \ V \ \hat{L}$$
$$\mathbf{T}_r \hat{L} = \sum_{i=1}^{N} f_r \ \max(G - b, 0) \ V \ \hat{L}$$

## **Bounded and Residual Light Transport**

=









indirect illumination represented as VPLs  $\hat{L}$ replaced by accurate indirect illumination  $(L - L_e)$ 



 $L_e + \mathbf{T}L_e + \mathbf{T}_e$ 

+

=

 $\mathbf{T}_r(L-L_e)$ 

 $\mathbf{T}_r \hat{L}$ 

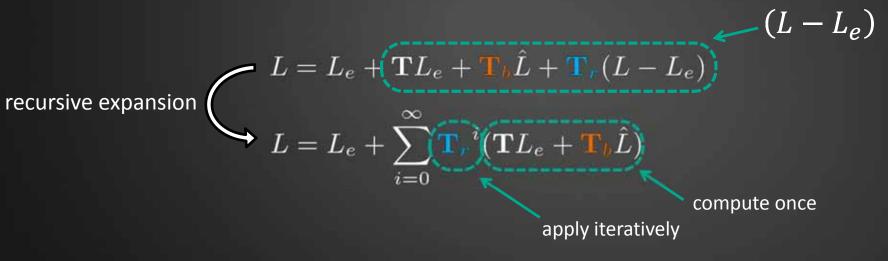
## **Bias Compensation**

#### **Bias Compensation [KK04]**

- $> T_r(L L_e)$  computed with MC integration
- can degenerate to path tracing: too expensive for real-time rendering

#### **Reformulated Bias Compensation**

- re-use the existing (clamped) solution
- iteratively apply the residual transport



design choice: compute and apply in screen-space



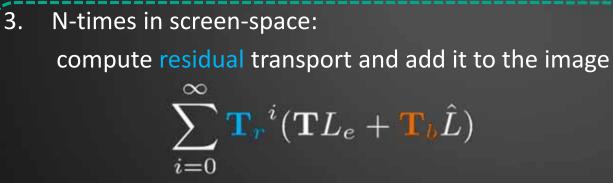
## **Screen-Space Bias Compensation**

#### Algorithm Overview

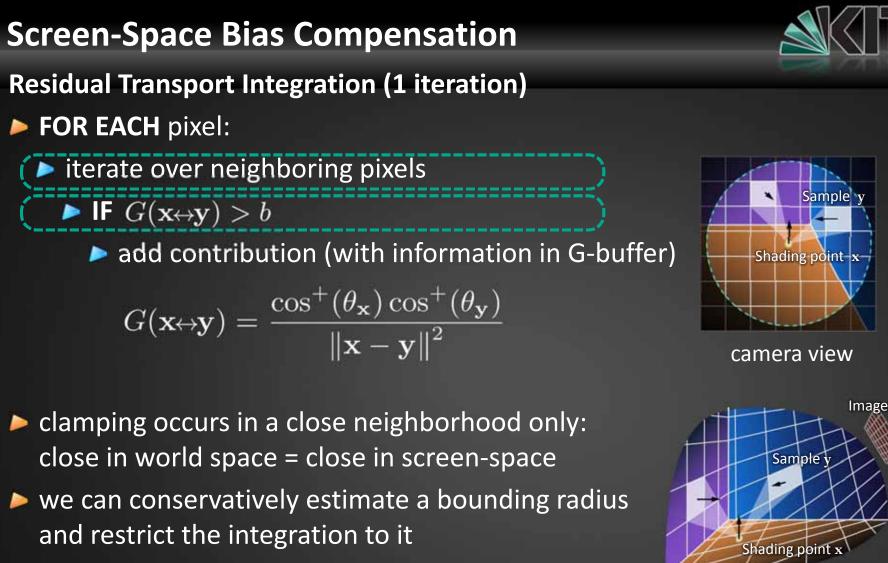
- precomputation
  - 1. distribute VPLs (as before)
  - 2. create an imperfect shadow map for every VPL

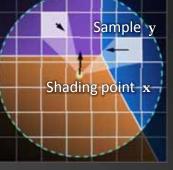
#### rendering

- 1. create deferred shading buffers
- 2. apply deferred direct and bounded VPL lighting  $\mathbf{T}L_e + \mathbf{T}_b \hat{L}$









camera view

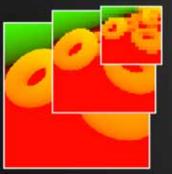
side view

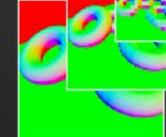
eve

## **Screen-Space Bias Compensation**

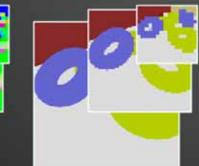
#### **Hierarchical Integration**

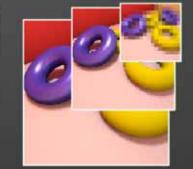
- still too many samples (even with the bounding radius)
- multi-resolution top-down integration (in spirit of [NW09])
- hierarchical approach requires
  - mip-map chain of the G-Buffer and bounded illumination
  - 🔊 discontinuity buffer





deferred shading buffers







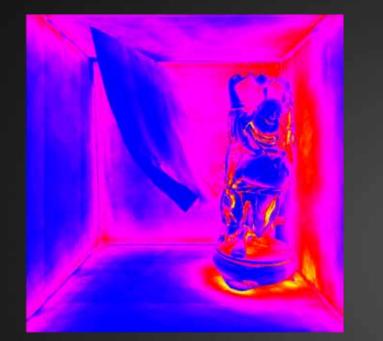
clamped solution discontinuity buffer

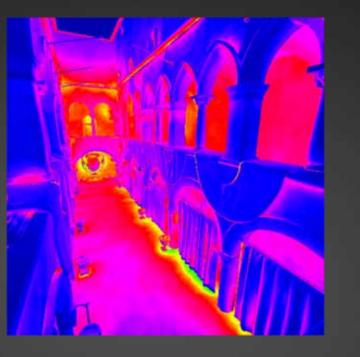
## **SSBC:** Hierarchical Integration

840

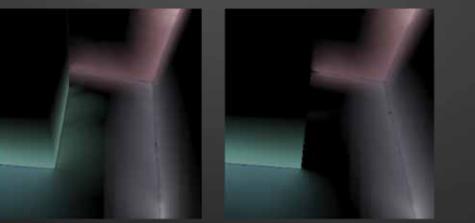
 $\cap$ 

#### number of samples (per pixel)





screen space always means: no information on hidden surfaces



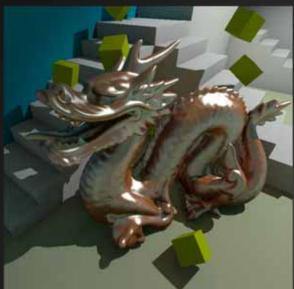
## **Screen Space Bias Compensation**



#### bounded light transport

### residual light transport



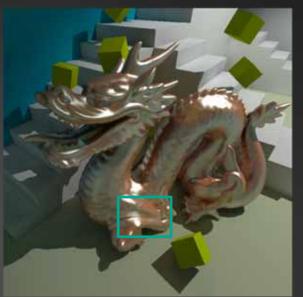


rendered with:

(ATI Radeon HD 5870)

1024x768 at:







no SSBC 10.3 FPS



1 iteration SSBC 8.2 FPS



2 iterations SSBC 6.4 FPS

## **Comparison to Ground Truth**

compensation only

result

bias compensation [KK04]

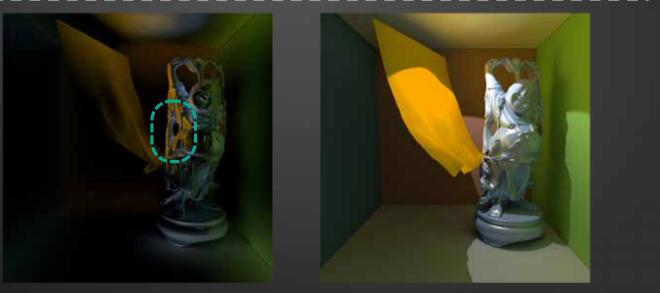
CPU ~ 10.9 hours (8-core, 4GB RAM)





screen-space bias compensation (3 steps)

GPU ~ 550 ms (ATI Radeon HD 5870)



# Participating Media with Many-Lights

### Light Transport in Participating Media

- direct light from surface VPLs and
- single-scattering from media VPLs (emit according to phase function)
- VPLs also generated at scattering events in media (see [ENSD12] for a step-by-step tutorial)



# **Rendering Strategies for Participating Media**

## Light Transport in Participating Media

- direct light from surface VPLs and
- single-scattering from media VPLs (emit according to phase function)

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VPLs also generated at scattering events in media (see [ENSD12] for a step-by-step tutorial)

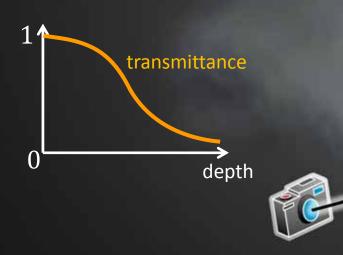
# Participating Media with Many-Lights

### Visibility and Transmittance

- le homogeneous media:
  - standard shadow map per VPL (compute transmittance)

#### heterogeneous media:

- shadow map plus ray marching or
- deep shadow maps [LV00] or
- adaptive volumetric SM [SVLL10]





# **Rendering Strategies for Participating Media**

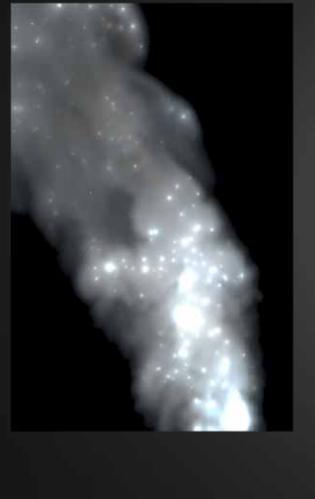
## Light Transport in Participating Media

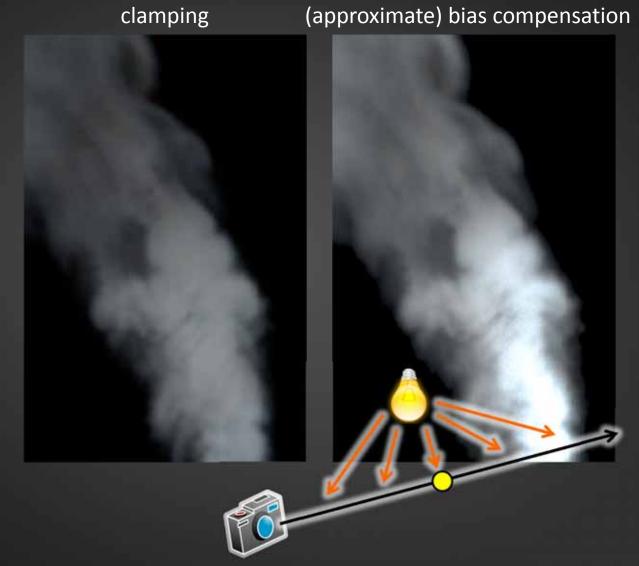
- direct light from surface VPLs and
- single-scattering from media VPLs (emit according to phase function)
- increased cost for visibility/transmittance computation
- observations to speed up bias compensation
  - how many compensation steps
  - heterogeneity vs. homogeneity
  - lassumptions on visibility
  - approximate bias compensation without ray casting!



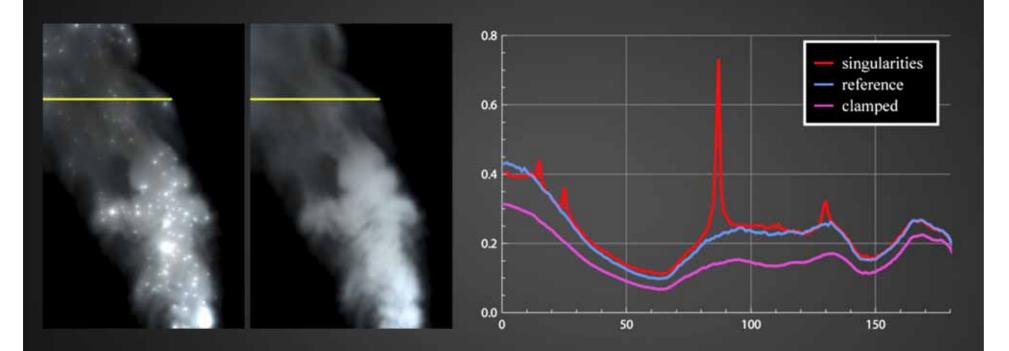
### **Bias Compensation**

no clamping





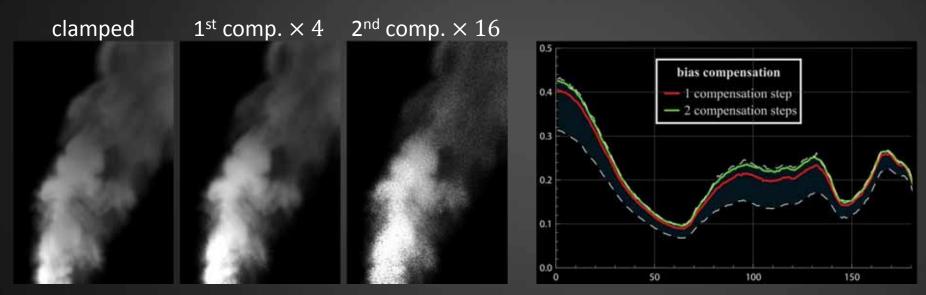
#### **Bias Compensation**





#### **Bias Compensation**

- classic bias compensation [RSK08] if prohibitively expensive
- similar to surface case: magnitudes of compensation steps drop quickly



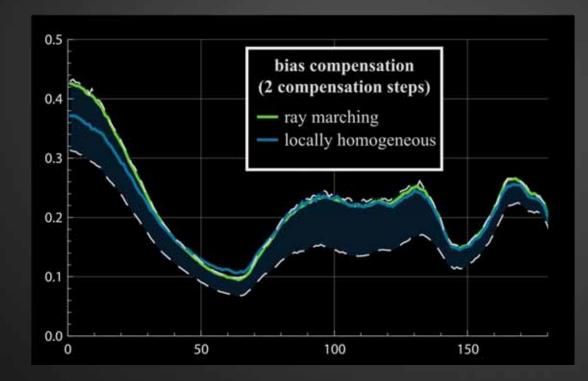
computed with path tracing (Raab et al.'s method)

### **Path Vertex Generation**

- goal: create new path vertices inside bounding region
- heterogeneous media: Woodcock tracing (rejection sampling) might create vertices that have to be omitted
- assume locally homogeneous media (= similar scattering properties in some proximity)
  - simple to create vertices only in bounding region
  - result still correct when transmittance τ computed with ray marching
  - see [ENSD12] for details!

### **Path Vertex Generation**

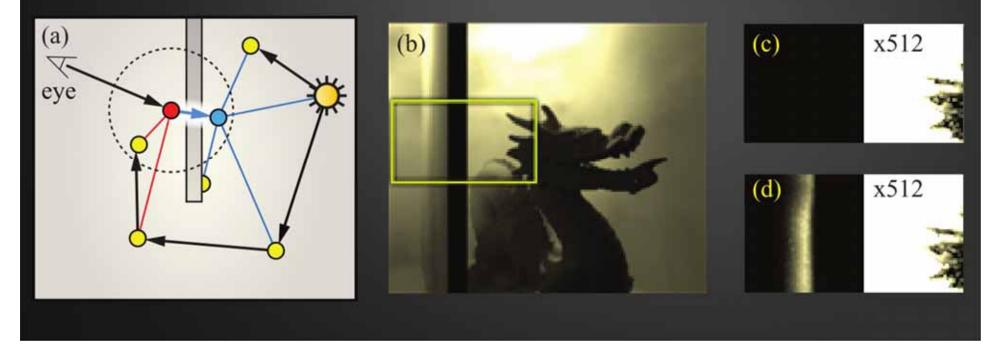
- assume media to be locally homogeneous
  - $\blacktriangleright$  simple to create vertices only in bounding region  $\checkmark$
- also compute transmittance using averaged scattering coefficients
  - not correct but very close





Do we have to compute visibility to newly created vertices?

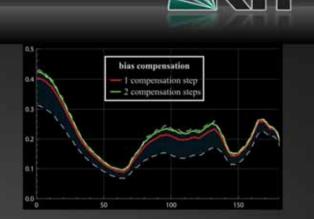
- New vertices are close to vertices requiring compensation
- what happens if we do not test mutual visibility?
- we tried to produce artifacts
  - vertices must be very close to a thin opaque object
  - medium must be thin (otherwise sampling through object unlikely)
  - quadratic decrease of compensation term



# **Many-Lights for Participating Media**

#### **Approximate Bias Compensation**

- VPL generation using ray casting
- two compensation steps only
- Iocally-homogeneous assumption
  - for creating new vertices without rejection
  - for computing transmittance to new vertices
- $\triangleright$  only transmittance au but no visibility to new vertices
- more details in the paper [ENSD12]



# **Approximate Bias Compensation**





# Conclusions



#### Famous Last Words...

- many-lights methods work quite well in real-time
  - bias compensation is feasible for surfaces and media
  - ▶ glossiness for surfaces ↔ anisotropic phase functions for media
  - for mostly diffuse scenes, for scenes with moderate anisotropic media



# Conclusions



- … about participating media and multiple scattering (MS)
  - MS does not really add new visual details (single scattering does)
  - but MS contributes a lot to the total energy (clamping is no option)



- and finally: it's all about visibility computation
  - rasterization to resolve from-point visibility (VPL generation and use)
  - rasterization for screen space integration

# **Optimizing Realistic Rendering with Many-Light Methods** Real-Time Many-Light Rendering

Acknowledgements:

Some slides on SSBC have been created by Jan Novak. Tobias Ritschel provided images for ISM/MR.



vovnik. Tolsins Rutschel provided i Intages for 1514//MIR

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